



# Influence of the Material Behavior Law and Damage Value on the Results of an Orthogonal Cutting Finite Element Model of Ti6Al4V



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# Introduction

- Modeling of machining processes:
  - Widely used in addition to experiments to provide a better understanding of cutting mechanics
  - Reduces costs by limiting the number of experiments
  - Provides access to hard-to-measure values such as temperature or residual stresses
- Machining = complex process → difficult to be modeled
- Model development involves many parameters influencing the results

- In this presentation:
  - Comparison between modeling and experimental results
  - Influence of material behavior law and damage value on the results will be studied
  
- Machined material
  - = Ti6Al4V
  - = titanium alloy often used in aeronautical and biomedical applications
  
- Known to be a difficult-to-machine material producing saw-toothed chips for some cutting conditions

# Plan

- A. Model presentation
- B. Experiments presentation
- C. Comparison between numerical and experimental results
- D. Improvement of the cutting force
- E. Improvement of the morphology
- F. Conclusions

# A. Model presentation

- Lagrangian Finite Element Method (FEM) model developed
  - to study the depth of cut influence on chip formation in orthogonal cutting [1]
  - with ABAQUS/Explicit
  - in 2D plane strain conditions
  
- Ducobu, F., Rivière-Lorphèvre, E., Filippi, E., 2011. *A Lagrangian FEM Model to Produce Saw-toothed Macro-chip and to Study the Depth of Cut Influence on its Formation in Orthogonal Cutting of Ti6Al4V*, Advanced Materials Research 223, p. 3.

- Cutting speed ( $V_c$ ): 30 m/min
- Depth of cut ( $h$ ): 280  $\mu\text{m}$
- Initial workpiece shape = rectangular box



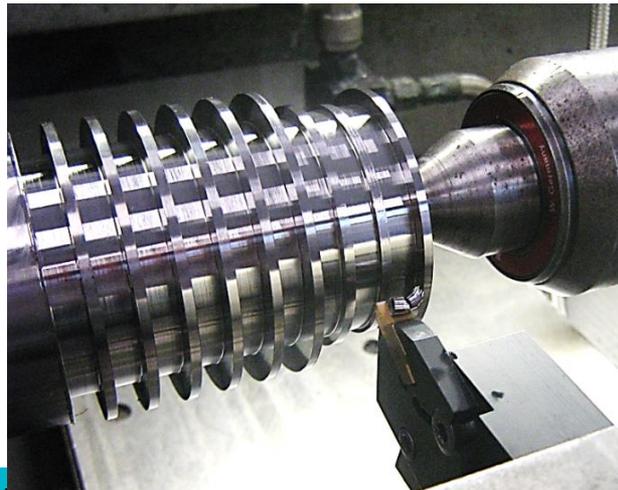
- Friction at the tool – chip interface implemented using Coulomb's friction ( $\mu = 0.05$ )
- All the friction energy is converted into heat
- Initial temperature set to 25°C
- Only conduction is considered and all the faces are adiabatic

- Workpiece material (Titanium alloy Ti6Al4V):
  - Behavior described by the Hyperbolic TANgent (TANH) law [2]
    - = Johnson-Cook law taking account of the strain softening effect
- Tool material: tungsten carbide described by a linear elastic law
  
- **Lagrangian** formulation → **chip separation criterion** needed
  - Chip formation possible thanks to an “eroding element” method
  - Criterion based on the temperature dependent tensile failure of Ti6Al4V

- Calamaz, M., Coupard, D., Girot, F., 2008. *A new material model for 2D numerical simulation of serrated chip formation when machining titanium alloy Ti-6Al-4V*, International Journal of Machine Tools and Manufacture 48, p. 275.

# B. Experiments presentation

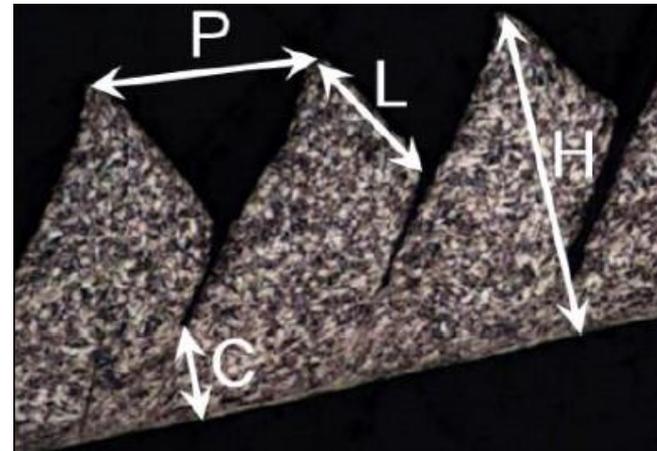
- Experiments performed on a lathe
- With the same cutting conditions as the numerical model
- In orthogonal cutting conditions
- Ti6Al4V annealed according to AMS 4928
- Forces measured with 9257B Kistler dynamometer



# C. Comparison with experimental results

- Experimental chips etched (Kroll's reagent) and polished before observation with an optical microscope
- To characterize a saw-toothed chip, 3 lengths are measured:

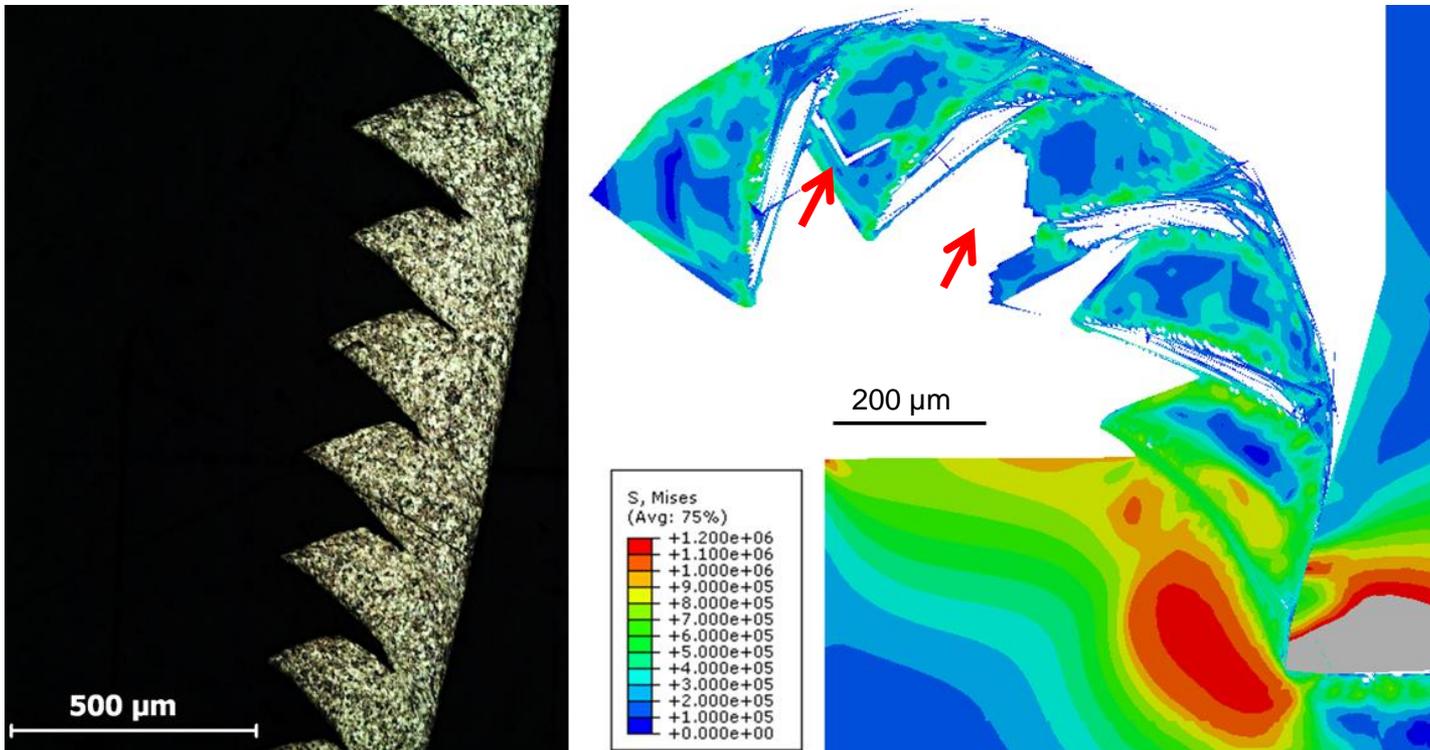
- L: Undeformed tooth length
- H: Height of the tooth
- C: Valley



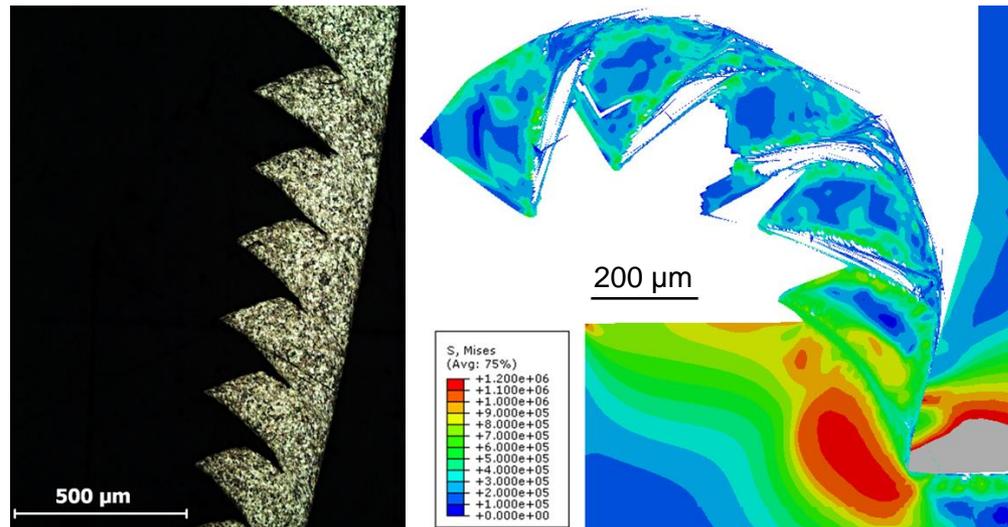
- Pitch (P) usually measured [5] but its value is modified (more than H and C) due to chip unrolling for observation

- Umbrello, D., 2008. *Finite element simulation of conventional and high speed machining of Ti6Al4V alloy*, Journal of Materials Processing Technology 196, p. 79.

- Experimental and numerical chips are saw-toothed
- Shapes qualitatively close to each other
- 2 differences are highlighted:
  - Numerical teeth are deeper (valley and underformed tooth length smaller)
  - Second and third contain a crack (so long for the 3<sup>rd</sup> that the tooth is broken)

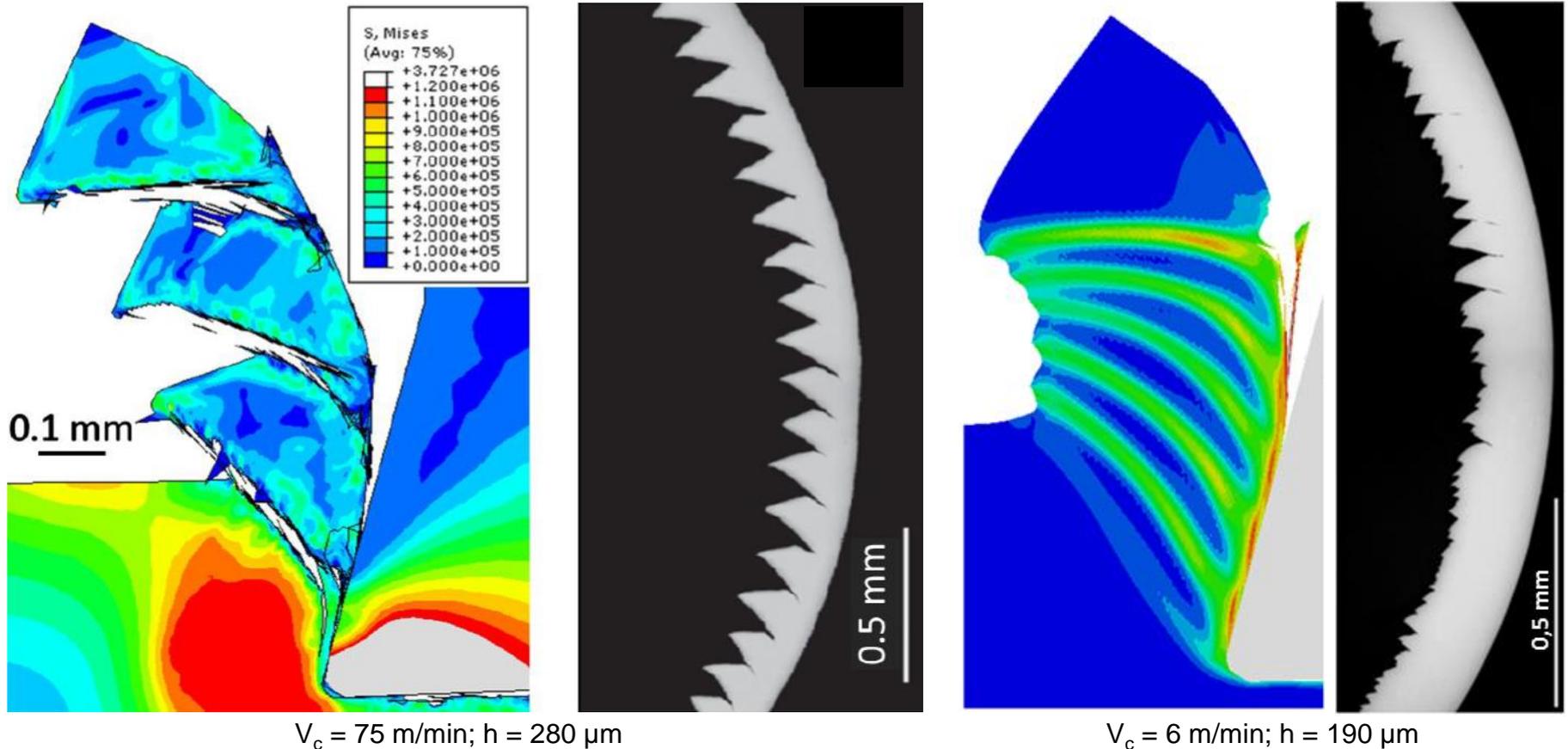


- Lower numerical valleys and tooth lengths
- teeth deformation is not sufficient + crack importance is too high
- Numerical chip formation mechanism: strong deformation in PSZ + crack propagation into it from its free surface to the tool



- When analyzing the microstructure of the experimental one: mechanisms very close → the numerical model takes correctly into account the physical phenomena
- It seems however that the crack propagates too easily in the model compared with the experiments

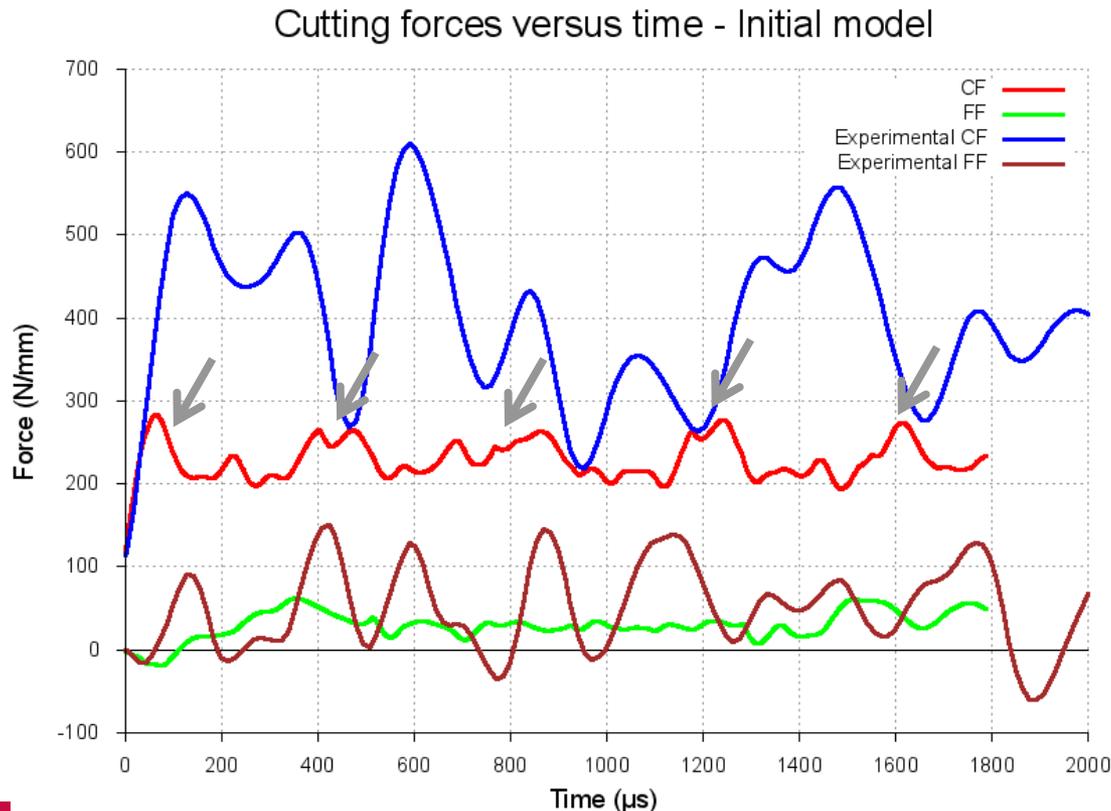
- Morphologies were compared for other cutting conditions [6]
- From saw-toothed to nearly continuous



- Numerical chips are qualitatively close to experimental ones

- Ducobu, F., 2013. *Contribution to the study of Ti6Al4V chip formation in orthogonal cutting. Numerical and experimental approaches for the comprehension of macroscopic and microscopic cutting mechanisms*, Ph.D. Thesis, UMONS.

- Cyclic evolution of the cutting force = typical of saw-toothed chip formation: a drop in the force = formation of a tooth
- Link between force evolution and teeth formation, 5 maxima = 5 teeth for the numerical chip
- Magnitudes of the variation of the experimental forces are much more important than the numerical ones



## ■ RMS values:

- The model largely underestimates the cutting force
- The feed force is very close to the experimental reference

	Experiments	Initial model
CF (N/mm)	387	231
Difference (%)	-	40
FF (N/mm)	77	72
Difference (%)	-	7

- We have no information on the Ti6Al4V metallurgical state used for the identification of the TANH law
  - Depending on the behavior law adopted the stresses vary greatly, leading to differences in the forces
- At this point, it is very likely that the TANH parameters do not correspond to our annealed Ti6Al4V

# D. Improvement of the cutting force

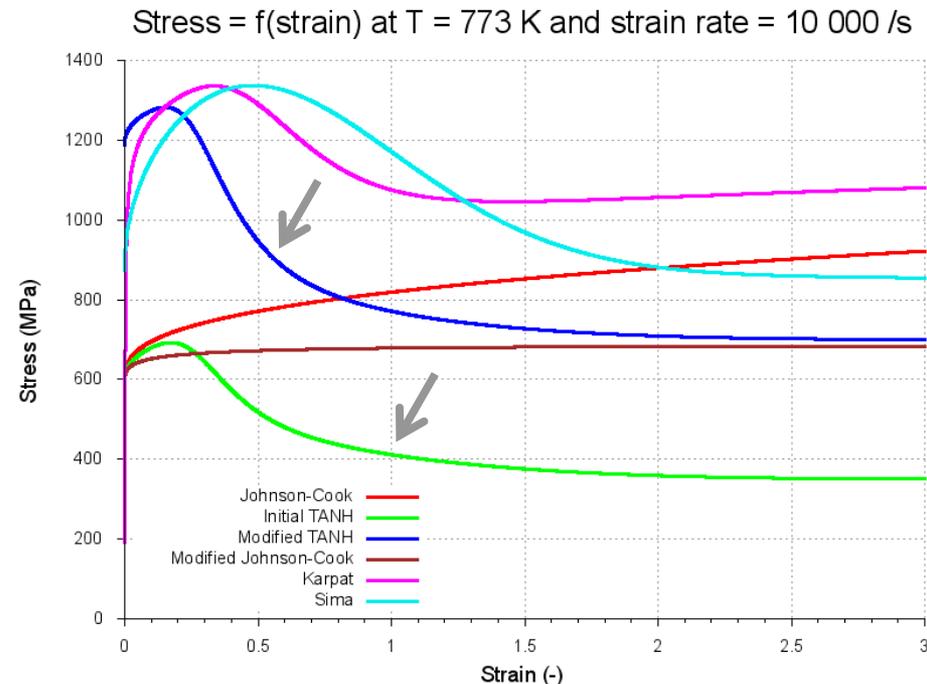
- First “adaptation” of the TANH parameters → higher cutting force

- Behavior of machined material + strain softening → many laws

- 2 groups: at small strains, stresses are nearly 2 x smaller → could explain the difference between numerical and experimental CF

- Proposition: pull the TANH curve up while maintaining its shape

- [2] Calamaz, M., Coupard, D., Girot, F., 2008. *A new material model for 2D numerical simulation of serrated chip formation when machining titanium alloy Ti-6Al-4V*, International Journal of Machine Tools and Manufacture 48, p. 275.
- [7] Calamaz, M., Coupard, D., Nouari, M., Girot, F., 2011. *Numerical analysis of chip formation and shear localisation processes in machining the Ti-6Al-4V titanium alloy*, International Journal of Advanced Manufacturing Technology 52, p. 887.
- [8] Karpap, Y., 2009. “*Finite element modeling of machining titanium alloy Ti-6Al-4V using a modified material model*”, 12th CIRP Conference on Modeling of Machining Operations. San Sebastian, Spain, p. 107.
- [9] Sima, M., Özel, T., 2010. *Modified material constitutive models for serrated chip formation simulations and experimental validation in machining of titanium alloy Ti-6Al-4V*, International Journal of Machine Tools and Manufacture 50, p. 943.

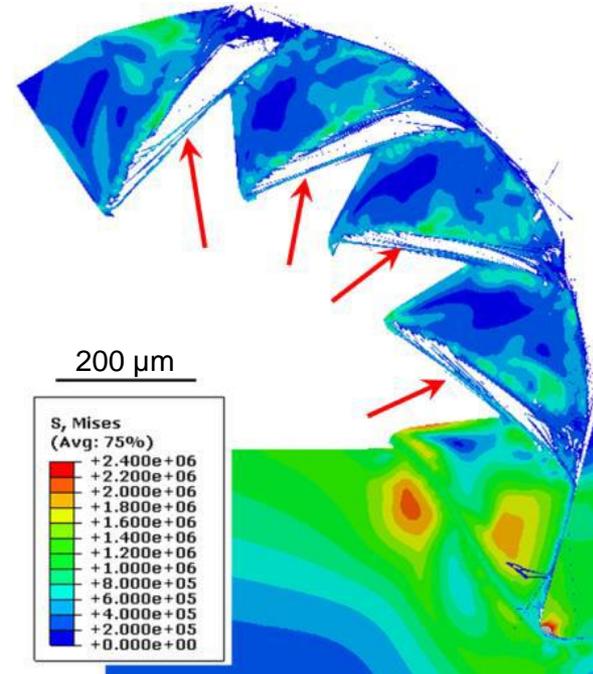


## Damage modification

- Using the modified TANH law in the model should results in a higher force thanks to larger stresses in the workpiece
- Tensile failure value reached faster → damage value must therefore also be modified
- In consistency with the behavior law, the temperature dependent tensile failure values are also doubled

## Results

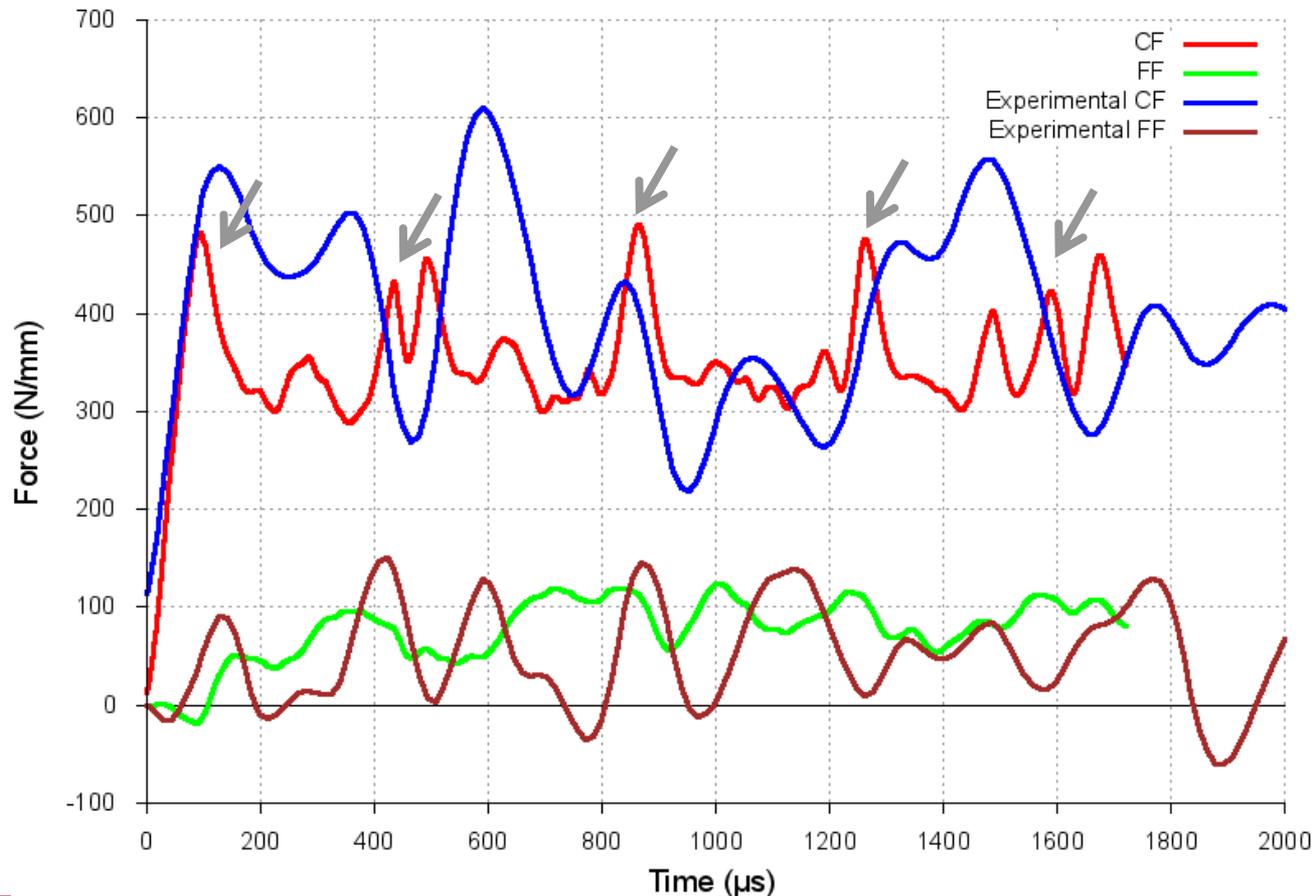
- Chip still saw-toothed, morphology still close to the experiments
- Some teeth are detaching during chip formation due to the conjunction of
  - Crack progressing in the PSZ
  - Second crack starting in the radius area of the tool



- Some elements link to successive teeth → it seems that the chip is still made of one piece
- The drawback observed with the initial TANH law is accentuated to the point of leading to a “discontinuous” chip

- Repercussion of the TANH law modification on CF:
  - higher level, now closer to the experiments
  - magnitude of the variations larger, now closer to the experiments
- As before feed forces are very close

Cutting forces versus time - Forces optimization



- The rise of the cutting force level → higher RMS value
  - The difference between the experimental and numerical CF and FF very small
- Similar, even smaller, than the best results in literature for Ti6Al4V for other cutting conditions:
- CF: 5%-10% and FF: 10%-15% [9-11]

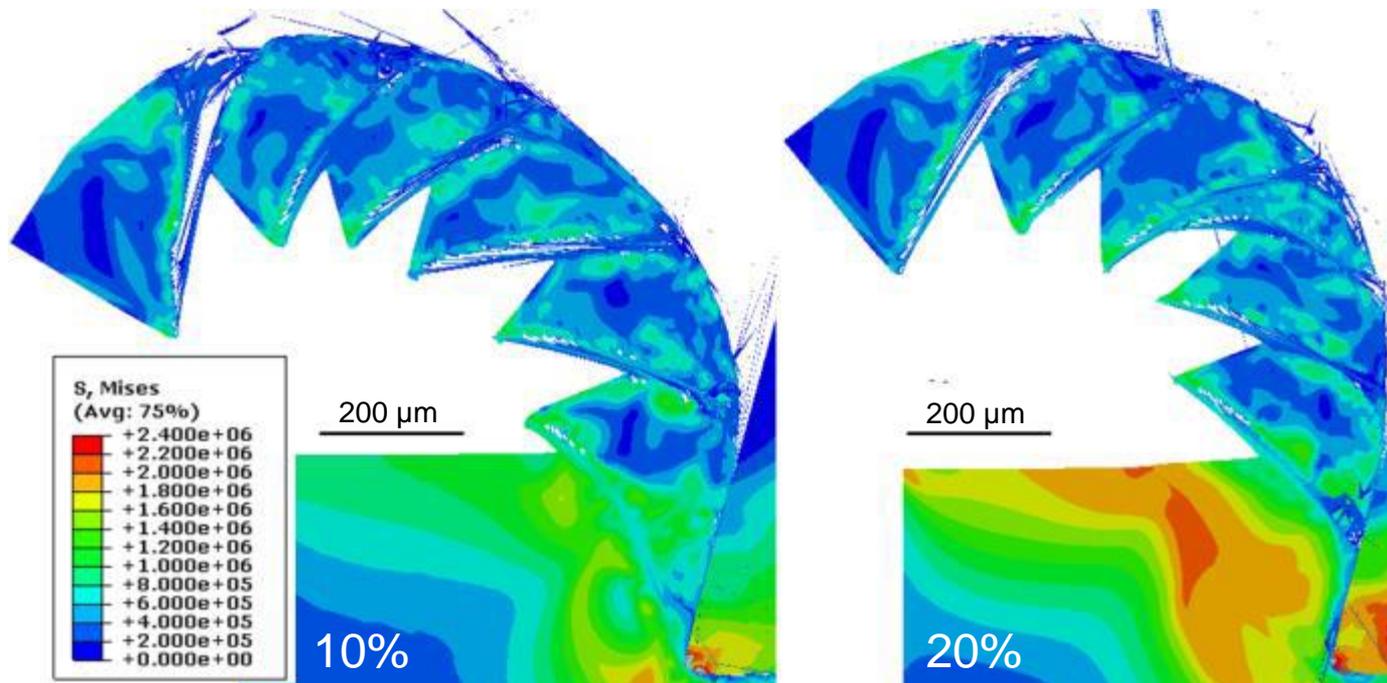
	Experiments	Initial model	Modified model
CF (N/mm)	387	231	361
Difference (%)	-	40	7
FF (N/mm)	77	72	86
Difference (%)	-	7	-12

- [9] Sima, M., Özel, T., 2010. *Modified material constitutive models for serrated chip formation simulations and experimental validation in machining of titanium alloy Ti-6Al-4V*, International Journal of Machine Tools and Manufacture 50, p. 943.
- [10] Karpát, Y., 2011. *Temperature dependent flow softening of titanium alloy Ti6Al4V: An investigation using finite element simulation of machining*, Journal of Materials Processing Technology 211, p. 737.
- [11] Zhang, Y.C., Mabrouki, T., Nelias, D., Gong, Y.D., 2011. *Chip formation in orthogonal cutting considering interface limiting shear stress and damage evolution based on fracture energy approach*, Finite Elements in Analysis and Design 47, p. 850.

# E. Improvement of the morphology

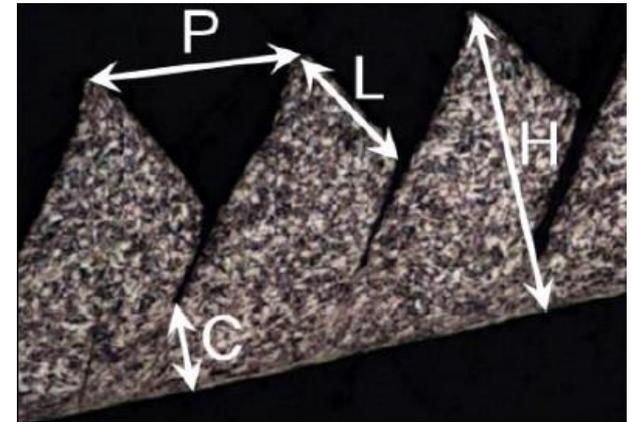
- Only the morphology now needs to be improved to get closer to the experimental one
- 2 previous models: crack propagates too quickly and easily  
→ increase of the damage value
- 2 modifications are considered:
  - Tensile values 10% higher than in the previous model
  - Tensile values 20% higher

- The two chips are saw-toothed and quite similar
  - Damage values 20% higher: no crack in the PSZ (except for the first tooth), contrary to the other chip → This damage value might therefore be too high
- the 10% higher case will be kept



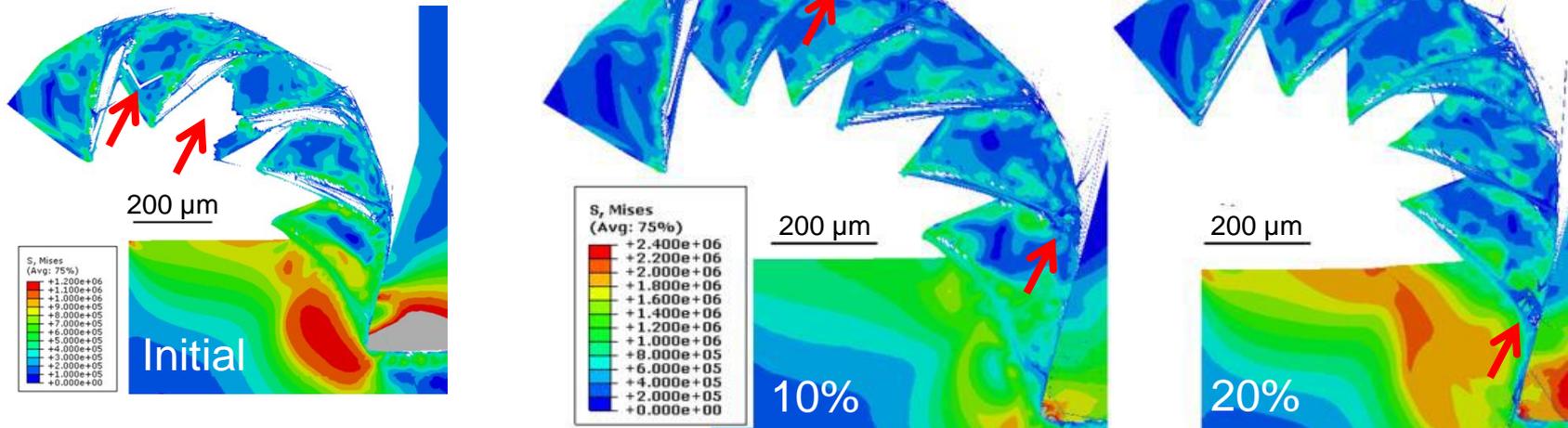
## Morphology

- Measurement of the three lengths
- The length (L) and the height (H) of the numerical teeth still lower than experimental values
  - about 27% for L
  - about 25% for H
- The valley (C) is now larger by round 30% = a maximum (and an overestimation because micro-cracks are not considered)



## Chip formation mechanism

- As for the experiments, the numerical chip formation = deformation + crack propagation



- For some teeth: second crack in the cutting edge radius area
  - Similar to the one observed for the first model with the modified TANH law
  - This drawback is therefore not completely eliminated
  - Rise of the damage value does not solve the problem (or at least in the proportions used here): the fifth tooth of the 20% higher model has also a crack like this
- No cracks in the teeth as in the first model = an improvement

## Forces

- The RMS values of the cutting forces can be considered as identical  
 → such results are not found in literature
- The feed force is higher than for the previous (and also initial) model

	Experiments	Initial model	Modified model	Final model
CF (N/mm)	387	231	361	378
Difference (%)	-	40	7	2
FF (N/mm)	77	72	86	106
Difference (%)	-	7	-12	-38

# F. Conclusions

- Main outline of this paper = partial decoupling between the morphology and the forces, at least within the limits of the variations selected
  - Forces level mainly influenced by the behavior law
  - Damage acts mostly on the chip morphology
- It is possible to modify one without greatly impacting the other
- Modifications of the TANH law can be justified by the initial difference with other laws found in literature as Kartpat's or Sima's
- Concerning damage, physical meaning must be used as no data are available to compare to the modified criterion

**Thank you for your attention**

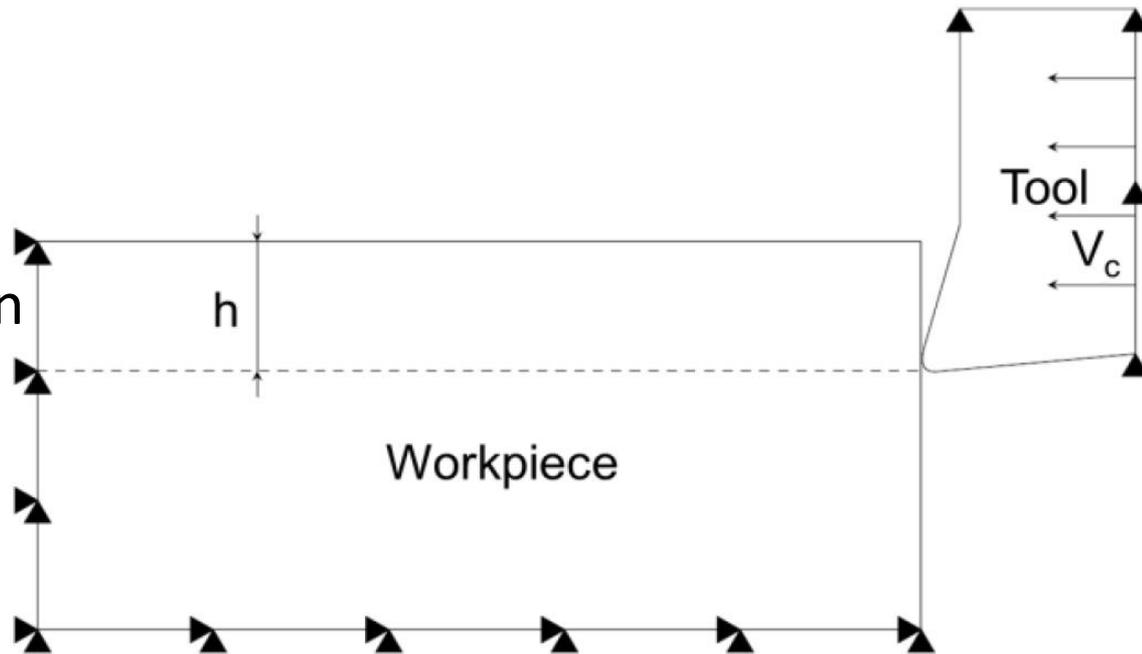
- Tool:

- Rake angle:  $15^\circ$
  - Clearance angle:  $2^\circ$
  - Edge radius:  $20\ \mu\text{m}$

- Cutting speed:  $30\ \text{m/min}$

- Depth of cut:  $280\ \mu\text{m}$

- Initial workpiece shape  
= rectangular box

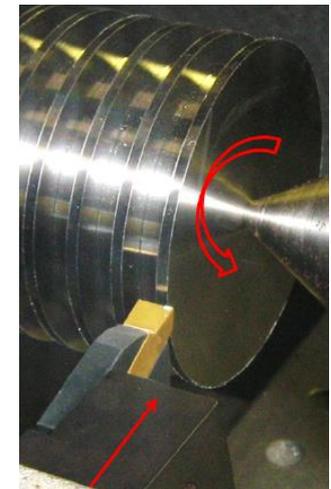
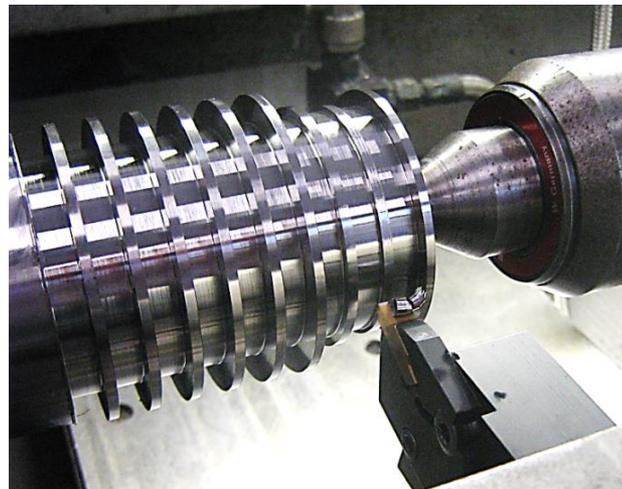


- Friction at the tool – chip interface implemented using Coulomb's friction
- All the friction energy is converted into heat
- Initial temperature set to  $25^\circ\text{C}$
- Only conduction is considered and all the faces are adiabatic

- **Lagrangian** formulation → **chip separation criterion** needed
- Chip formation possible thanks to an “eroding element” method
- Criterion based on the temperature dependent tensile failure of Ti6Al4V
  
- Tensile failure value reached in an element  
→ deleted from the visualization  
and all its stress components are put to zero
- Suppression of a finite element  
→ introduction of a crack in the workpiece  
→ making it possible for the chip to come off

## Orthogonal cutting conditions

- Workpiece specimen = shaft comporting flanges in the form of successive slices (diameter 60 mm) of equal thickness (2 mm)
- Tool and tool holder custom made by SECO in order to provide the same characteristics as the numerical model
- Tool width larger than disks width to satisfy plain strain conditions
- Use of a tailstock to avoid workpiece displacements and vibrations
- Forces measured with 9257B Kistler dynamometer



## TANH modification

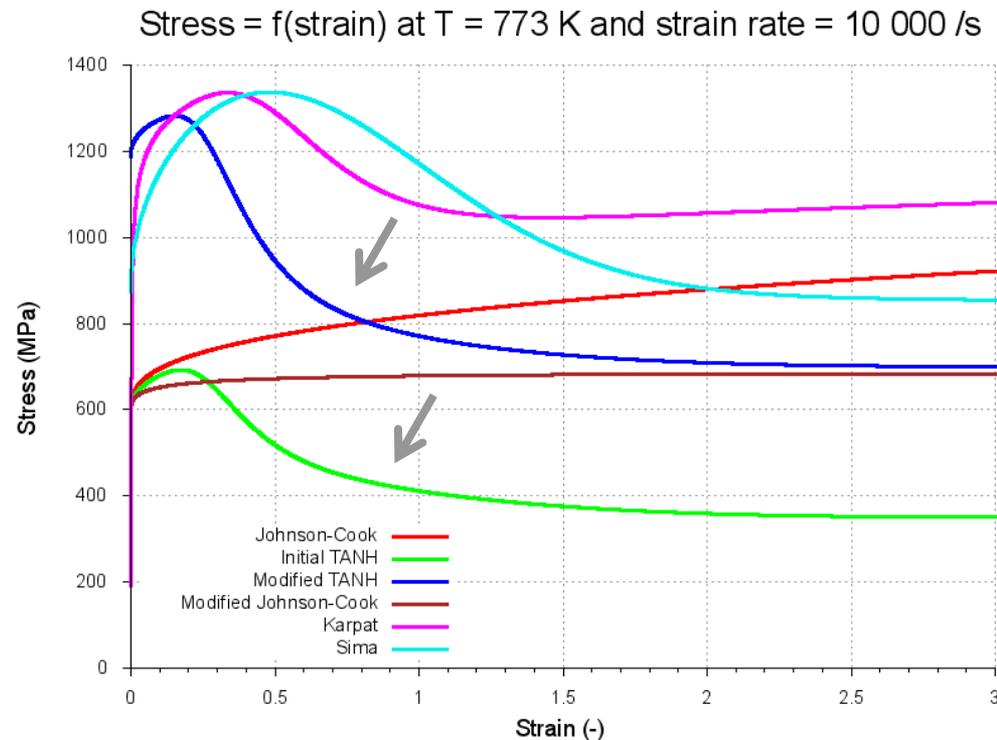
- Proposition: pull the TANH curve up while maintaining its shape
- “Level modification” performed acting on the A parameter
- Numerical force  $\approx 40\%$  smaller than the experiments  $\rightarrow$  the value of A is doubled
- $\rightarrow$  Level of modified TANH law closer to Karpat and Sima laws

$$\sigma = \left[ A + B \varepsilon^n \left( \frac{1}{\exp(\varepsilon^a)} \right) \right] \left[ 1 + C \ln \frac{\dot{\varepsilon}}{\dot{\varepsilon}_0} \right]$$

$$\left[ 1 - \left( \frac{T - T_{room}}{T_{melt} - T_{room}} \right)^m \right] \left[ D + (1 - D) \tanh \left( \frac{1}{(\varepsilon + S)^c} \right) \right]$$

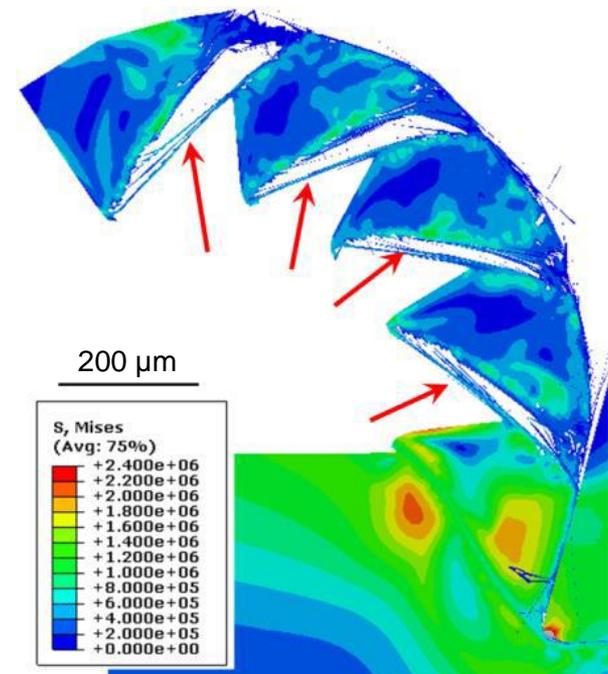
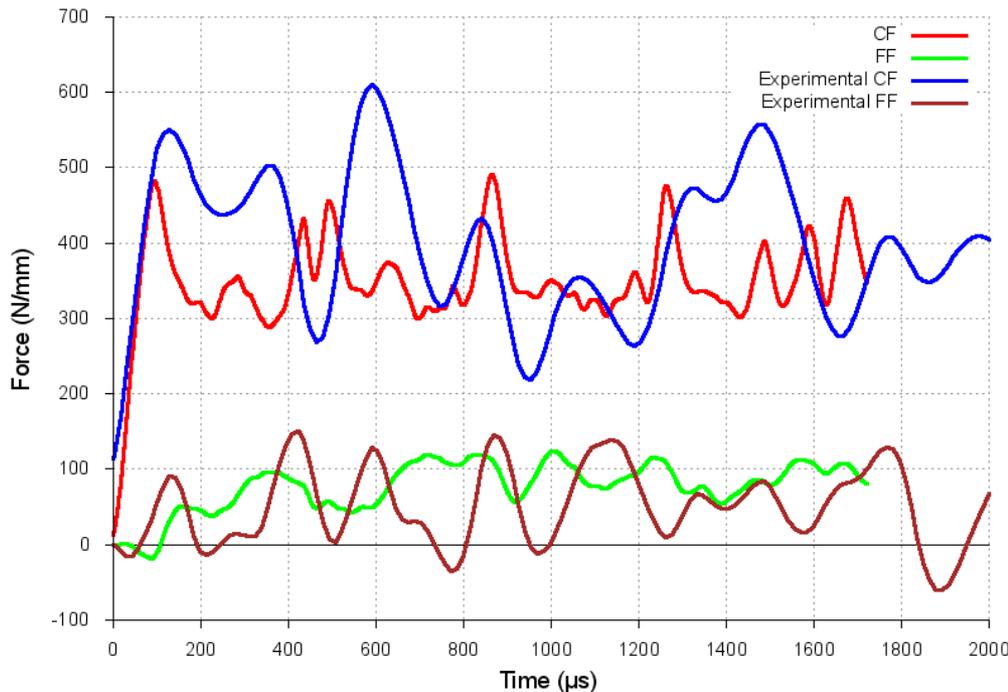
with

$$D = 1 - \left( \frac{T}{T_{melt}} \right)^d \text{ and } S = \left( \frac{T}{T_{melt}} \right)^b$$



- The only notable difference between the two cutting forces is the width of the peaks, larger for the experimental case
- Due to the removal of the teeth:
  - it leads to a quick drop in the force
  - the tool has to move more to be again in contact with the workpiece and the force rises again

Cutting forces versus time - Forces optimization

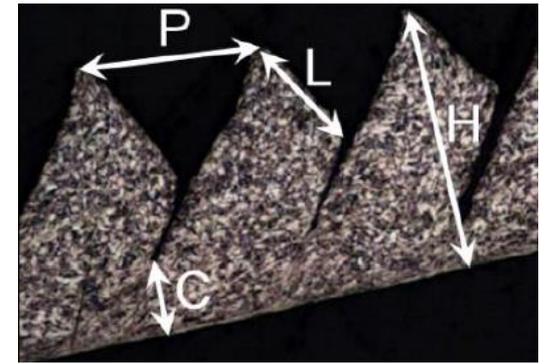


## Conclusions: the results are mixed

- Chip morphology deteriorated: problem identified in the initial model → amplified
  - ✓ Level of the cutting force closer to the experiments = this increase = the main objective of the TANH law modification → the model fulfills its role on this point
  - Modification the behavior and damage laws in the same proportions → mainly the cutting force is affected
- The behavior law would therefore mainly acts on the level of the forces without affecting the morphology

## Morphology

- Measurement of the three lengths
- Measuring the valley is not easy:
  - micro-cracks in PSZ of the third, fourth and fifth teeth without coming out of the free surface
  - not taken into account, certainly resulting in an overestimation of this value (no micro-cracks were experimentally observed)
- The length (L) and the height (H) of the numerical teeth still lower than experimental values
  - about 27% for L
  - about 25% for H
- The valley (C) is now larger by round 30% = a maximum (and an overestimation because micro-cracks are not considered)



- The final results are very satisfying:
  - ✓ The cutting force is close to the measured one
  - ✓ The morphology is similar to these of the experimental chip
  - ✓ The formation mechanism implies deformation and crack propagation in both cases
  - ✓ The teeth are not too deep anymore and the valley value is closer to the experimental one
  
- The parasitical cracks observed in some teeth are not present anymore but others smaller appear in the primary shear zone near the cutting edge radius area
  
- The feed force is on the contrary overestimated
- Micro-cracks are also observed in the primary shear zone for the numerical chip, none were identified during the experiments